Sum, multiple, sideslip, inversion and differential of hyperfunction
5th May. 2014
Kobayasi Tamotu
(1) Operation at each point

Sum, multiple, sideslip, inversion and differential are operations at each point. When function $J(x)$ which is the result of operation performed on approximate functions is used as approximate function, components $j_{h}(x), j_{d}(x), j_{1}(x), j_{2}(x), \cdots \cdot$ are computed by formula(1) ~formula (4)

$$
\begin{align*}
& \mathrm{j}_{\mathrm{h}}(\mathrm{x})=\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} J(\mathrm{x}-\rho)  \tag{1}\\
& \mathrm{j}_{\mathrm{d}}(\mathrm{x})=\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0}\{J(\mathrm{x}+\rho)-J(\mathrm{x}-\rho)\}  \tag{2}\\
& \mathrm{j}_{1}(\mathrm{x})=\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \int_{\mathrm{x}-\rho}^{\mathrm{x}+\rho} J(\mathrm{t}) \mathrm{dt}  \tag{3}\\
& \mathrm{j}_{\mathrm{n}}(\mathrm{x})=\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \int_{\mathrm{x}-\rho}^{\mathrm{x}+\rho}(\mathrm{t}-\mathrm{x})^{\mathrm{n}-1} J(\mathrm{t}) \mathrm{dt} \tag{4}
\end{align*}
$$

Hyperfunction which is the result of operation is defined as formula(5) in which components $j_{h}(x), j_{d}(x), j_{1}(x), j_{2}(x), \cdots$ are seperated with cmma" , " lined up in brakets " \{ \}".

$$
\begin{equation*}
\mathrm{j}(\mathrm{x})=\left\{\mathrm{j}_{\mathrm{h}}(\mathrm{x}), \mathrm{j}_{\mathrm{d}}(\mathrm{x}), \mathrm{j}_{1}(\mathrm{x}), \mathrm{j}_{2}(\mathrm{x}), \cdots \cdot\right\} \tag{5}
\end{equation*}
$$

Multiple, sideslip, inversion and differential are operations performed on 1 hyperfunction $f(x)$. Sum is an operation performed on 2 hyperfunctions $\mathrm{f}(\mathrm{x})$ and $\mathrm{g}(\mathrm{x})$. As far as sum, multiple, sideslip, inversion and differential are concerned, operations can be defined, because all components converge.
(2) Sum, multiple, sideslip

Function $J(x)$ calculated by formula (6) defines sum of hyperfunctions $f(x)$ and $g(x)$. Function $F(x)$ and $G(x)$ are the approximate function of hyperfunction $f(x)$ and $g(x)$.

$$
\begin{equation*}
J(x)=F(x)+G(x) \tag{6}
\end{equation*}
$$

With respect to components, formula (7) ~ formula (10) holds.

$$
\begin{align*}
& \mathrm{j}_{\mathrm{h}}(\mathrm{x})=\mathrm{f}_{\mathrm{h}}(\mathrm{x})+\mathrm{g}_{\mathrm{h}}(\mathrm{x})  \tag{7}\\
& \left.\mathrm{j}_{\mathrm{d}} \mathrm{x}\right)=\mathrm{f}_{\mathrm{d}}(\mathrm{x})+\mathrm{g}_{\mathrm{d}}(\mathrm{x})  \tag{8}\\
& \mathrm{j}_{1}(\mathrm{x})=\mathrm{f}_{1}(\mathrm{x})+\mathrm{g}_{1}(\mathrm{x})  \tag{9}\\
& \mathrm{j}_{\mathrm{n}}(\mathrm{x})=\mathrm{f}_{\mathrm{n}}(\mathrm{x})+\mathrm{g}_{\mathrm{n}}(\mathrm{x}) \tag{10}
\end{align*}
$$

Function $J(x)$ calculated by formula (11) using constant c defines muitiple of hyperfunction of $f(x)$.

$$
\begin{equation*}
J(x)=c \cdot F(x) \tag{11}
\end{equation*}
$$

With respect to components, formula(12)~ formula (15) holds.

$$
\begin{align*}
& \mathrm{j}_{\mathrm{h}}(\mathrm{x})=\mathrm{c} \cdot \mathrm{f}_{\mathrm{h}}(\mathrm{x})  \tag{12}\\
& \mathrm{j}_{\mathrm{d}}(\mathrm{x})=\mathrm{c} \cdot \mathrm{f}_{\mathrm{d}}(\mathrm{x})  \tag{13}\\
& \mathrm{j}_{1}(\mathrm{x})=\mathrm{c} \cdot \mathrm{f}_{\mathrm{i}}(\mathrm{x})  \tag{14}\\
& \mathrm{j}_{\mathrm{n}}(\mathrm{x})=\mathrm{c} \cdot \mathrm{f}_{\mathrm{n}}(\mathrm{x}) \tag{15}
\end{align*}
$$

Function $J(x)$ calculated by formula (16) using constant a defines sideslip of hyperfunction $f(x)$.

$$
\begin{equation*}
J(x)=F(x-a) \tag{16}
\end{equation*}
$$

With respect to components, formula(17)~ formula (20) holds.

$$
\begin{align*}
& \mathrm{j}_{\mathrm{h}}(\mathrm{x})=\mathrm{f}_{\mathrm{h}}(\mathrm{x}-\mathrm{a})  \tag{17}\\
& \mathrm{j}_{\mathrm{d}}(\mathrm{x})=\mathrm{f}_{\mathrm{d}}(\mathrm{x}-\mathrm{a})  \tag{18}\\
& \mathrm{j}_{1}(\mathrm{x})=\mathrm{f}_{1}(\mathrm{x}-\mathrm{a})  \tag{19}\\
& \mathrm{j}_{\mathrm{n}}(\mathrm{x})=\mathrm{f}_{\mathrm{n}}(\mathrm{x}-\mathrm{a}) \tag{20}
\end{align*}
$$

As far as sum, multiple and sideslip are concerned, computing formulas of all components are the same form as computing formulas of approximate function.

Function $J(x)$ calculated by formula (21) defines differnce of hyperfunctions $f(x)$ and $g(x)$.

$$
\begin{equation*}
J(x)=F(x)-G(x)=F(x)+(-1) \cdot G(x) \tag{21}
\end{equation*}
$$ formula(21) is explained as combination of multiple of -1 and sum.

## (3) Inversion

Function $\mathrm{J}(\mathrm{x})$ calculated by formula (22) defines inversion of hyperfunction $f(x)$.

$$
\begin{equation*}
\mathrm{J}(\mathrm{x})=\mathrm{F}(-\mathrm{x}) \tag{22}
\end{equation*}
$$

With respect to components, formula(23) ~ formula (26) holds.

$$
\begin{align*}
& \mathrm{j}_{\mathrm{h}}(\mathrm{x})=\mathrm{f}_{\mathrm{d}}(-\mathrm{x})+\mathrm{f}_{\mathrm{h}}(-\mathrm{x})  \tag{23}\\
& \mathrm{j}_{\mathrm{d}}(\mathrm{x})=-\mathrm{f}_{\mathrm{d}}(-\mathrm{x})  \tag{24}\\
& \mathrm{j}_{\mathrm{n}}(\mathrm{x})=\mathrm{f}_{\mathrm{n}}(-\mathrm{x}) \quad(\mathrm{n}=1,3,5, \cdot \cdot \cdot)  \tag{25}\\
& \mathrm{j}_{\mathrm{n}}(\mathrm{x})=-\mathrm{f}_{\mathrm{n}}(-\mathrm{x}) \quad(\mathrm{n}=2,4,6, ~ \cdot \cdot \cdot) \tag{26}
\end{align*}
$$

Among formula (23) ~formula (26) which calculate components, only formula (25) is the same form as formula(22) which is computing formula of approximate function.
(4) Differentioal

Function $J(x)$ calculated by formula (27) defines differntial of hyperfunction $f(x)$.

$$
\begin{equation*}
J(x)=F^{\prime}(x) \tag{27}
\end{equation*}
$$

With respect to components, formula(28) ~ formula(32) holds.

$$
\begin{align*}
& \mathrm{j}_{\mathrm{h}}(\mathrm{x})=\lim _{\rho \rightarrow 0}\left(\mathrm{f}_{\mathrm{h}}\right)^{\prime}(\mathrm{x}-\rho)  \tag{28}\\
& \mathrm{j}_{\mathrm{d}}(\mathrm{x})=\lim _{\rho \rightarrow 0}\left\{\left(\mathrm{f}_{\mathrm{h}}\right)^{\prime}(\mathrm{x}+\rho)-\left(\mathrm{f}_{\mathrm{h}}\right)^{\prime}(\mathrm{x}-\rho)\right\}  \tag{29}\\
& \mathrm{j}_{1}(\mathrm{x})=\mathrm{f}_{\mathrm{d}}(\mathrm{x})  \tag{30}\\
& \mathrm{j}_{2}(\mathrm{x})=-\mathrm{f}_{1}(\mathrm{x})  \tag{31}\\
& \mathrm{j}_{\mathrm{n}}(\mathrm{x})=-(\mathrm{n}-1) \mathrm{f}_{\mathrm{n}-1}(\mathrm{x}) \tag{32}
\end{align*}
$$

As far as differntial is conerned, among formula (28) $\sim$ formula (32) which calculate components, no formula is the same form as formula (27) which is computing formula of approximate function. Left continuous component $\mathrm{j}_{\mathrm{h}}(\mathrm{x})$, step component $\mathrm{j}_{\mathrm{d}}(\mathrm{x})$ are expressed using ( $\mathrm{f}_{\mathrm{h}}$ ) ( x ) which is derivative
of left continuous component $f_{h}(x)$. First component $\mathrm{j}_{1}(\mathrm{x})$ is coincides with step component $\mathrm{f}_{\mathrm{d}}(\mathrm{x})$. As for higher components than second, $n$-th component $j_{n}(x)$ is coincides with -( $\mathrm{n}-1$ ) multiple of ( $\mathrm{n}-1$ )-th component $\mathrm{f}_{\mathrm{n}-1}(\mathrm{x})$.
(5) Examples of calculation

From function $J(x)$ expressed by formula (6), component $\mathrm{j}_{1}(\mathrm{x})$ is computed as formula (33), substituting function $J(x)$ into formula(3), and component $j_{1}(x)$ converges.

$$
\begin{align*}
\mathrm{j}_{1}(\mathrm{x}) & =\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \int_{x-\rho}^{x+\rho} J(\mathrm{t}) \mathrm{dt} \\
& =\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \int_{x-\rho}^{x+\rho}\{\mathrm{F}(\mathrm{t})+\mathrm{G}(\mathrm{t})\} \mathrm{dt} \\
& =\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \int_{x-\rho}^{x+\rho} \mathrm{F}(\mathrm{t}) \mathrm{dt}+\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \int_{x-\rho}^{x+\rho} G(\mathrm{t}) \mathrm{dt} \\
& =\mathrm{f}_{1}(\mathrm{x})+\mathrm{g}_{1}(\mathrm{x}) \tag{33}
\end{align*}
$$

Formula(33) explains that formula (9) holds.
From function $J(x)$ expressed by formula (22), component $\mathrm{j}_{\mathrm{h}}(\mathrm{x})$ is computed as formula(34), substituting function $\mathrm{J}(\mathrm{x})$ into formula(1), and component $j_{1}(x)$ converges.

$$
\begin{align*}
& \mathrm{j}_{\mathrm{h}}(\mathrm{x})=\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \mathrm{~J}(\mathrm{x}-\rho)=\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \mathrm{~F}(-\mathrm{x}-\rho) \\
& =\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \mathrm{~F}\{-(\mathrm{x}+\rho)\} \\
& =\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0}[\mathrm{~F}\{-(\mathrm{x}+\rho)\}-\mathrm{F}\{-(\mathrm{x}-\rho)\}+\mathrm{F}\{-(\mathrm{x}-\rho)\}] \\
& =\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0}[\mathrm{~F}\{-(\mathrm{x}+\rho)\}-\mathrm{F}\{-(\mathrm{x}-\rho)\}] \\
& \quad+\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \mathrm{~F}\{-(\mathrm{x}-\rho)\} \\
& =\mathrm{f}_{\mathrm{d}}(-\mathrm{x})+\mathrm{f}_{\mathrm{h}}(-\mathrm{x}) \tag{34}
\end{align*}
$$

Formula(34) explains that formula (23) holds.
With respect to sum, multiple, sideslip, inversion and differential, components can be calculated by the similar way as formula(33), formula(34).

